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## Chapter 11

# Differential equations

### First-order equations

11.1  $\dot{x}(t) = f(t) \iff x(t) = x(t_0) + \int_{t_0}^t f(\tau) d\tau$

A simple differential equation and its solution.  $f(t)$  is a given function and  $x(t)$  is the unknown function.

11.2  $\frac{dx}{dt} = f(t)g(x) \iff \int \frac{dx}{g(x)} = \int f(t) dt$   
Evaluate the integrals. Solve the resulting implicit equation for  $x = x(t)$ .

A *separable* differential equation. If  $g(a) = 0$ ,  $x(t) \equiv a$  is a solution.

11.3  $\dot{x} = g(x/t)$  and  $z = x/t \implies t \frac{dz}{dt} = g(z) - z$

A *projective* differential equation. The substitution  $z = x/t$  leads to a separable equation for  $z$ .

11.4 The equation  $\dot{x} = B(x-a)(x-b)$  has the solutions  
$$x \equiv a, \quad x \equiv b, \quad x = a + \frac{b-a}{1 - Ce^{B(b-a)t}}$$

$a \neq b$ .  $a = 0$  gives the *logistic* equation.  $C$  is a constant.

11.5  $\bullet \dot{x} + ax = b \iff x = Ce^{-at} + \frac{b}{a}$   
 $\bullet \dot{x} + ax = b(t) \iff x = e^{-at}(C + \int b(t)e^{at} dt)$

*Linear first-order differential equations with constant coefficient*  
 $a \neq 0$ .  $C$  is a constant.

11.6  $\dot{x} + a(t)x = b(t) \iff$   
$$x = e^{-\int a(t) dt} \left( C + \int e^{\int a(t) dt} b(t) dt \right)$$

*General linear first-order differential equation.*  
 $a(t)$  and  $b(t)$  are given.  
 $C$  is a constant.

11.7	$\dot{x} + a(t)x = b(t) \iff$ $x(t) = x_0 e^{-\int_{t_0}^t a(\xi) d\xi} + \int_{t_0}^t b(\tau) e^{-\int_{\tau}^t a(\xi) d\xi} d\tau$	<p>Solution of (11.6) with given initial condition <math>x(t_0) = x_0</math>.</p>
11.8	<p><math>\dot{x} + a(t)x = b(t)x^r</math> has the solution</p> $x(t) = e^{-A(t)} \left[ C + (1-r) \int b(t) e^{(1-r)A(t)} dt \right]^{\frac{1}{1-r}}$ <p>where <math>A(t) = \int a(t) dt</math>.</p>	<p><i>Bernoulli's</i> equation and its solution (<math>r \neq 1</math>). <math>C</math> is a constant. (If <math>r = 1</math>, the equation is separable.)</p>
11.9	$\dot{x} = P(t) + Q(t)x + R(t)x^2$	<p><i>Riccati's</i> equation. Not analytically solvable in general. The substitution <math>x = u + 1/z</math> works if we know a particular solution <math>u = u(t)</math>.</p>
11.10	<p>The differential equation</p> $(*) \quad f(t, x) + g(t, x) \dot{x} = 0$ <p>is called <i>exact</i> if <math>f'_x(t, x) = g'_t(t, x)</math>. The solution <math>x = x(t)</math> is then given implicitly by the equation <math>\int_{t_0}^t f(\tau, x) d\tau + \int_{x_0}^x g(t_0, \xi) d\xi = C</math> for some constant <math>C</math>.</p>	<p>An <i>exact</i> equation and its solution.</p>
11.11	<p>A function <math>\beta(t, x)</math> is an <i>integrating factor</i> for <math>(*)</math> in (11.10) if <math>\beta(t, x)f(t, x) + \beta(t, x)g(t, x)\dot{x} = 0</math> is exact.</p> <ul style="list-style-type: none"> <li>• If <math>(f'_x - g'_t)/g</math> is a function of <math>t</math> alone, then <math>\beta(t) = \exp[\int (f'_x - g'_t)/g dt]</math> is an integrating factor.</li> <li>• If <math>(g'_t - f'_x)/f</math> is a function of <math>x</math> alone, then <math>\beta(x) = \exp[\int (g'_t - f'_x)/f dx]</math> is an integrating factor.</li> </ul>	<p>Results which occasionally can be used to solve equation <math>(*)</math> in (11.10).</p>
11.12	<p>Consider the <i>initial value problem</i></p> $(*) \quad \dot{x} = F(t, x), \quad x(t_0) = x_0$ <p>where <math>F(t, x)</math> and <math>F'_x(t, x)</math> are continuous over the rectangle</p> $\Gamma = \{ (t, x) :  t - t_0  \leq a,  x - x_0  \leq b \}$ <p>Define</p> $M = \max_{(t, x) \in \Gamma}  F(t, x) , \quad r = \min(a, b/M)$ <p>Then <math>(*)</math> has a unique solution <math>x(t)</math> on the open interval <math>(t_0 - r, t_0 + r)</math>, and <math> x(t) - x_0  \leq b</math> in this interval.</p>	<p>A (local) <i>existence and uniqueness theorem</i>.</p>